

## ONE-WAY ANALYSIS OF VARIANCE MODEL

- The simplest type of analysis of variance
- Generalizes the two-sample equal variance t-test situation to more than two groups.

### *The situation:*

1. *Response variable*  $Y$  (e.g., score on exam)
2.  $v$  populations  $G_1, G_2, \dots, G_v$  on which the response variable is defined.
  - e.g., "treatment groups":  $G_i$  is the population that has received the  $i^{\text{th}}$  treatment (or: the  $i^{\text{th}}$  level of the treatment factor)
3.  $Y_i$ : response for the population  $G_i$ .
  - i.e.,  $Y_i = Y|G_i$ ,  $Y$  restricted to  $G_i$ .
4.  $\mu_i$  = the mean of  $Y$  on the  $i^{\text{th}}$  population  $G_i$ .
  - i.e.,  $\mu_i = E(Y_i) = E(Y|G_i)$
  - $\mu_i$  is sometimes called the *true mean* for the  $i^{\text{th}}$  treatment or population.
5.  $\varepsilon_i = Y_i - \mu_i$ .
  - $\varepsilon_i$  is a new random variable
  - $\varepsilon_i = i^{\text{th}}$  error

*Example:* Testing computer packages to teach a programming language, but comparing 3 such packages rather than 2.

- $Y =$
- $v =$
- $G_i =$
- $\mu_i =$

### *Note:*

- (5) can be re-expressed as  $Y_i = \mu_i + \varepsilon_i$
- *model equations*
- a *linear* or *additive* model.
- *means model*.

**Model assumptions:**

1. For each  $i$ , we take a simple random sample of size  $r_i$  from population  $G_i$ .
2. The samples are independent.
3. Each  $\varepsilon_i$  is normally distributed.
4. All  $\varepsilon_i$ 's have the same variance  $\sigma^2$ .

**Comments:**

1. For an experiment, assumptions (1) and (2) can be combined to say that *experimental units are randomly assigned to treatments*, subject only to the constraint that the sample size for the  $i^{\text{th}}$  treatment is  $r_i$ . i.e., the experiment is *completely randomized*.
2. *Balanced design*: When all  $r_i$ 's are equal.
3. Assumptions (3) and (4) combined:  $\varepsilon_i \sim N(0, \sigma^2)$
4. Note similarities to a linear regression model with indicator variables representing a categorical variable.

**Alternate formulations of the model equations.**

1. Letting  $\mu = E(Y)$  (the *overall population mean*) and  $\tau_i = \mu_i - \mu$ , the model equation becomes:

$$Y_i = \mu + \tau_i + \varepsilon_i.$$

- $\tau_i$  : the *effect* of the  $i^{\text{th}}$  treatment on the response.
- " *effects model*"

2. In terms of the sample random variables:

$Y_{it}$  = the random variable giving the response from the  $t^{\text{th}}$  observation from  $G_i$  (e.g., the response from the  $t^{\text{th}}$  observation of the  $i^{\text{th}}$  treatment).

$$\varepsilon_{it} = Y_{it} - \mu_i.$$

The model equation becomes:

$$Y_{it} = \mu_i + \varepsilon_{it}$$

$$\text{or } Y_{it} = \mu + \tau_i + \varepsilon_{it}.$$

Model assumptions become:

- a) The  $\varepsilon_{it}$  are independent random variables.
- b) For each  $i$  and  $t$ ,  $\varepsilon_{it} \sim N(0, \sigma^2)$

*Note:* This is a *fixed effects model*: We are assuming that we have specified treatments fixed by the experimenter. So the  $\tau_i$ 's are parameters.

A generalization: The treatments are a random sample from a larger population of treatments. So the  $\tau_i$ 's are random variables. (*random effects model* -- discussed in Chapter 17.)

### ***Dot notation***

Convenient notational conventions:

- A dot in a subscript position means "add over all values of the subscript in that position."

Examples:

$$Y_{i\cdot} = \sum_{t=1}^{r_i} Y_{it} \quad Y_{\cdot t} = \sum_{i=1}^v Y_{it} \quad Y_{\cdot\cdot} = \sum_{i=1}^v \sum_{t=1}^{r_i} Y_{it}$$

- A bar over the variable as well as a dot in the subscript position means: divide by the number of possibilities for the subscript as well as add over all values of the subscript. (i.e., take the average over all values of the subscript.)

Example:

$$\bar{Y}_{i\cdot} = \frac{1}{r_i} \sum_{t=1}^{r_i} Y_{it}$$

More examples: