THE MULTIPLE LINEAR REGRESSION MODEL

Notation:

p predictors x_1, x_2, \ldots, x_p k-1 *non-constant* terms $u_1, u_2, \ldots, u_{k-1}$ Each u_j is a function of x_1, x_2, \ldots, x_p : $u_{j=}u_j(x_1, x_2, \ldots, x_p)$ For convenience, we often set $u_0 = 1$ (constant function)

The Basic Multiple Linear Regression Model: Two assumptions:

 $\begin{aligned} 1. \ E(Y|\underline{x}) &= \eta_0 + \eta_1 u_1 + \ldots + \eta_{k-1} u_{k-1} \quad \text{(Linear Mean Function)} \\ 2. \ Var(Y|\underline{x}) &= \sigma^2 \quad \text{(Constant Variance)} \end{aligned}$

Assumption (1) in vector notation:

$$\underline{\mathbf{u}} = \begin{bmatrix} u_0 \\ u_1 \\ \mathbf{M} \\ u_{k-1} \end{bmatrix} = \begin{bmatrix} 1 \\ u_1 \\ \mathbf{M} \\ u_{k-1} \end{bmatrix}, \qquad \underline{\mathbf{n}} = \begin{bmatrix} \eta_0 \\ \eta_1 \\ \mathbf{M} \\ \eta_{k-1} \end{bmatrix}$$

Then $\underline{\eta}^{T} = [\eta_0 \ \eta_1 \dots \ \eta_{k-1}]$ and

$$\underline{\mathbf{n}}^{\mathrm{T}}\underline{\mathbf{u}} = \mathbf{\eta}_{0} + \mathbf{\eta}_{1}\mathbf{u}_{1} + \ldots + \mathbf{\eta}_{k-1}\mathbf{u}_{k-1},$$
so (1) becomes:

(1')
$$E(Y|\underline{x}) = \underline{\eta}^{T}\underline{u}$$

If we have data with i^{th} observation $x_{i1}, x_{i2}, \ldots, x_{ip}, y_i$, recall

$$\underline{\mathbf{x}}_{i} = \begin{bmatrix} x_{i1} \\ x_{i2} \\ \mathbf{M} \\ x_{ip} \end{bmatrix} = [\mathbf{x}_{i1}, \mathbf{x}_{i2}, \dots, \mathbf{x}_{ip}]^{\mathrm{T}}$$

Define similarly

 $u_{ij} = u_j (x_1, x_2, ..., x_p)$ = the value of the jth term for the ith observation, and

$$\underline{\mathbf{u}}_{j} = \begin{bmatrix} u_{i0} \\ u_{i1} \\ \mathbf{M} \\ u_{i,k-1} \end{bmatrix}$$

So in particular, the model says

$$E(Y|\underline{x}_i) = \underline{\eta}^T \underline{u}_i$$

Estimation of Parameters: Analogously to the case of simple linear regression, consider functions ("hyperplanes") of the form

$$\mathbf{y} = \mathbf{h}_0 + \mathbf{h}_1 \mathbf{u}_1 + \ldots + \mathbf{h}_{k-1} \mathbf{u}_{k-1} = \underline{\mathbf{h}}^{\mathrm{T}} \underline{\mathbf{u}}.$$

The *least squares estimate* of \underline{n} is the vector

$$\hat{\underline{\eta}} = egin{bmatrix} \hat{\eta}_0 \ \hat{\eta}_1 \ M \ \hat{\eta}_{k-1} \end{bmatrix}$$

that minimizes the "objective function"

$$\mathbf{RSS}(\underline{\mathbf{h}}) = \sum_{i=1}^{n} (y_i - \underline{\mathbf{h}}^T \underline{\mathbf{u}}_i)^2$$

Recall: In simple linear regression, the solution had $SXX = \sum_{i=1}^{n} (x_i - \overline{x})^2$ in the

denominator. So the formula won't work if all x_i 's = \overline{x} . In this case, there is not a unique solution to the least squares problem. (Draw a picture in the case n = 2!)

In multiple regression: There is a unique solution $\hat{\eta}$ provided:

i) k < n (the number of terms is less than the number of observations)
ii) no u_i is (as a function) a linear combination of the other u_i's

When (ii) is violated, we say there is (strict) multicollinearity.

If there is a unique solution, it is called the *ordinary least squares (OLS) estimate* of the (vector of) coefficients.