THE MULTIPLE LINEAR REGRESSION MODEL

Notation:

p predictors x_1, x_2, \ldots, x_p k-1 *non-constant* terms $u_1, u_2, \ldots, u_{k-1}$ Each u_j is a function of x_1, x_2, \ldots, x_p : $u_{j=}u_{j}(x_1, x_2, \ldots, x_p)$ For convenience, we often set $u_0 = 1$ (constant function/term)

The Basic Multiple Linear Regression Model: Two assumptions:

- 1. $E(Y|\underline{x}) = \eta_0 + \eta_1 u_1 + ... + \eta_{k-1} u_{k-1}$ (Linear Mean Function)
- 2. $Var(Y|x) = \sigma^2 (Or: Var(Y|u) = \sigma^2)$ (Constant Variance)

Assumption (1) in vector notation:

$$\underline{\mathbf{u}} = \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ \vdots \\ u_{k-1} \end{bmatrix} = \begin{bmatrix} 1 \\ u_1 \\ \vdots \\ \vdots \\ u_{k-1} \end{bmatrix}, \qquad \underline{\mathbf{\eta}} = \begin{bmatrix} \boldsymbol{\eta}_0 \\ \boldsymbol{\eta}_1 \\ \vdots \\ \vdots \\ \boldsymbol{\eta}_{k-1} \end{bmatrix}$$

Then $\underline{\boldsymbol{\eta}}^{T} = [\boldsymbol{\eta}_{0} \ \boldsymbol{\eta}_{1} \dots \ \boldsymbol{\eta}_{k-1}]$ and

 $\underline{\eta}^{T}\underline{u} = \eta_{0} + \eta_{1}u_{1} + ... + \eta_{k-1}u_{k-1},$ so (1) becomes:

(1')
$$E(Y|\underline{x}) = \eta^{T}\underline{u}$$

If we have data with i^{th} observation $x_{i1}, x_{i2}, \dots, x_{ip}, y_i$, recall

$$\underline{\mathbf{x}}_{i} = \begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ \vdots \\ x_{ip} \end{bmatrix} = [\mathbf{x}_{i1}, \mathbf{x}_{i2}, \dots, \mathbf{x}_{ip}]^{T}$$

Define similarly

 $u_{ij} = u_j (x_{i1}, x_{i2}, \dots, x_{ip})$ = the value of the j^{th} term for the i^{th} observation, and

$$\underline{\mathbf{u}}_{\mathbf{i}} = egin{bmatrix} u_{i0} \\ u_{i1} \\ \vdots \\ \vdots \\ u_{i,k-1} \end{bmatrix}$$

So in particular, the model says

$$E(Y|\underline{x}_i) = \eta^T \underline{u}_i$$

Estimation of Parameters: Analogously to the case of simple linear regression, consider functions ("hyperplanes") of the form

$$y = h_0 + h_1 u_1 + \ldots + h_{k\text{--}1} u_{k\text{--}1} = \underline{h}^T \underline{u}.$$

The *least squares estimate* of $\underline{\eta}$ is the vector

$$\hat{\underline{\eta}} = egin{bmatrix} \hat{\eta}_0 \ \hat{\eta}_1 \ \mathsf{M} \ \hat{\eta}_{k-1} \end{bmatrix}$$

that minimizes the "objective function"

$$RSS(\underline{\mathbf{h}}) = \sum_{i=1}^{n} (y_i - \underline{\mathbf{h}}^T \underline{\mathbf{u}}_i)^2$$

Recall: In simple linear regression, the solution had $SXX = \sum_{i=1}^{n} (x_i - \overline{x})^2$ in the

denominator. So the formula won't work if all x_i 's = \overline{x} . In this case, there is not a unique solution to the least squares problem. (Draw a picture in the case n = 2!)

In multiple regression: There is a unique solution $\hat{\underline{\eta}}$ provided:

- i) k < n (the number of terms is less than the number of observations)
- ii) no \boldsymbol{u}_j is (as a function) a linear combination of the other \boldsymbol{u}_j 's

When (ii) is violated, we say there is (strict) multicollinearity.

If there is a unique solution, it is called the *ordinary least squares (OLS) estimate* of the (vector of) coefficients.